

Programmable Controller

MELSEC iQ-R

MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Startup)

-RJ71EIP91

SAFETY PRECAUTIONS

(Read these precautions before using this product.)

Before using this product, please read this manual and the relevant manuals carefully and pay full attention to safety to handle the product correctly.

The precautions given in this manual are concerned with this product only. For the safety precautions of the programmable controller system, refer to the CPU module User's Manual used.

In this manual, the safety precautions are classified into two levels: " WARNING" and " CAUTION".

WARNING

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

A CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Under some circumstances, failure to observe the precautions given under "ACAUTION" may lead to serious consequences.

Observe the precautions of both levels because they are important for personal and system safety.

Make sure that the end users read this manual and then keep the manual in a safe place for future reference.

[Design Precautions]

WARNING

- Configure safety circuits external to the programmable controller to ensure that the entire system
 operates safely even when a fault occurs in the external power supply or the programmable controller.
 Failure to do so may result in an accident due to an incorrect output or malfunction.
 - (1) Emergency stop circuits, protection circuits, and protective interlock circuits for conflicting operations (such as forward/reverse rotations or upper/lower limit positioning) must be configured external to the programmable controller.
 - (2) When the programmable controller detects an abnormal condition, it stops the operation and all outputs are:
 - Turned off if the overcurrent or overvoltage protection of the power supply module is activated.
 - Held or turned off according to the parameter setting if the self-diagnostic function of the CPU module detects an error such as a watchdog timer error.
 - (3) All outputs may be turned on if an error occurs in a part, such as an I/O control part, where the CPU module cannot detect any error. To ensure safety operation in such a case, provide a safety mechanism or a fail-safe circuit external to the programmable controller. For a fail-safe circuit example, refer to "General Safety Requirements" in the MELSEC iQ-R Module Configuration Manual.
 - (4) Outputs may remain on or off due to a failure of a component such as a relay and transistor in an output circuit. Configure an external circuit for monitoring output signals that could cause a serious accident.
- In an output circuit, when a load current exceeding the rated current or an overcurrent caused by a load short-circuit flows for a long time, it may cause smoke and fire. To prevent this, configure an external safety circuit, such as a fuse.

[Design Precautions]

WARNING

- Configure a circuit so that the programmable controller is turned on first and then the external power supply. If the external power supply is turned on first, an accident may occur due to an incorrect output or malfunction.
- For the operating status of each station after a communication failure, refer to manuals relevant to the network. Incorrect output or malfunction due to a communication failure may result in an accident.
- When connecting an external device with a CPU module or intelligent function module to modify data of a running programmable controller, configure an interlock circuit in the program to ensure that the entire system will always operate safely. For other forms of control (such as program modification, parameter change, forced output, or operating status change) of a running programmable controller, read the relevant manuals carefully and ensure that the operation is safe before proceeding. Improper operation may damage machines or cause accidents.
- Especially, when a remote programmable controller is controlled by an external device, immediate action cannot be taken if a problem occurs in the programmable controller due to a communication failure. To prevent this, configure an interlock circuit in the program, and determine corrective actions to be taken between the external device and CPU module in case of a communication failure.
- Do not write any data to the "system area" and "write-protect area" of the buffer memory in the module. Also, do not use any "use prohibited" signals as an output signal from the CPU module to each module. Doing so may cause malfunction of the programmable controller system. For the "system area", "write-protect area", and the "use prohibited" signals, refer to the user's manual for the module used.
- If a communication cable is disconnected, the network may be unstable, resulting in a communication failure of multiple stations. Configure an interlock circuit in the program to ensure that the entire system will always operate safely even if communications fail. Failure to do so may result in an accident due to an incorrect output or malfunction.
- To maintain the safety of the programmable controller system against unauthorized access from external devices via the network, take appropriate measures. To maintain the safety against unauthorized access via the Internet, take measures such as installing a firewall.
- For the operating status of each EtherNet/IP device after a communication failure, refer to the MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application). Incorrect output or malfunction due to a communication failure may result in an accident.
- Configure an interlock circuit in the program to ensure that the entire system will always operate safely even if communications fail in multiple EtherNet/IP devices. Failure to do so may result in an accident due to an incorrect output or malfunction.

[Design Precautions]

- Do not install the control lines or communication cables together with the main circuit lines or power cables. Keep a distance of 100mm or more between them. Failure to do so may result in malfunction due to noise.
- During control of an inductive load such as a lamp, heater, or solenoid valve, a large current (approximately ten times greater than normal) may flow when the output is turned from off to on. Therefore, use a module that has a sufficient current rating.
- After the CPU module is powered on or is reset, the time taken to enter the RUN status varies
 depending on the system configuration, parameter settings, and/or program size. Design circuits so
 that the entire system will always operate safely, regardless of the time.
- Do not power off the programmable controller or reset the CPU module while the settings are being written. Doing so will make the data in the flash ROM and SD memory card undefined. The values need to be set in the buffer memory and written to the flash ROM and SD memory card again. Doing so also may cause malfunction or failure of the module.
- When changing the operating status of the CPU module from external devices (such as the remote RUN/STOP functions), select "Do Not Open by Program" for "Opening Method" of "Module Parameter". If "Open by Program" is selected, an execution of the remote STOP function causes the communication line to close. Consequently, the CPU module cannot reopen the line, and external devices cannot execute the remote RUN function.

[Installation Precautions]

WARNING

 Shut off the external power supply (all phases) used in the system before mounting or removing the module. Failure to do so may result in electric shock or cause the module to fail or malfunction.

[Installation Precautions]

- Use the programmable controller in an environment that meets the general specifications in the Safety Guidelines included with the base unit. Failure to do so may result in electric shock, fire, malfunction, or damage to or deterioration of the product.
- To mount a module, place the concave part(s) located at the bottom onto the guide(s) of the base unit, and push in the module until the hook(s) located at the top snaps into place. Incorrect interconnection may cause malfunction, failure, or drop of the module.
- To mount a module with no module fixing hook, place the concave part(s) located at the bottom onto the guide(s) of the base unit, push in the module, and fix it with screw(s). Incorrect interconnection may cause malfunction, failure, or drop of the module.
- When using the programmable controller in an environment of frequent vibrations, fix the module with a screw.
- Tighten the screws within the specified torque range. Undertightening can cause drop of the screw, short circuit, or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, or malfunction.
- When using an extension cable, connect it to the extension cable connector of the base unit securely.
 Check the connection for looseness. Poor contact may cause malfunction.
- When using an SD memory card, fully insert it into the SD memory card slot. Check that it is inserted completely. Poor contact may cause malfunction.
- Securely insert an extended SRAM cassette or a battery-less option cassette into the cassette
 connector of the CPU module. After insertion, close the cassette cover and check that the cassette is
 inserted completely. Poor contact may cause malfunction.
- Do not directly touch any conductive parts and electronic components of the module, SD memory card, extended SRAM cassette, battery-less option cassette, or connector. Doing so can cause malfunction or failure of the module.

[Wiring Precautions]

WARNING

- Shut off the external power supply (all phases) used in the system before installation and wiring. Failure to do so may result in electric shock or cause the module to fail or malfunction.
- After installation and wiring, attach a blank cover module (RG60) to each empty slot and an included extension connector protective cover to the unused extension cable connector before powering on the system for operation. Failure to do so may result in electric shock.

[Wiring Precautions]

- Individually ground the FG and LG terminals of the programmable controller with a ground resistance of 100 ohms or less. Failure to do so may result in electric shock or malfunction.
- Use applicable solderless terminals and tighten them within the specified torque range. If any spade solderless terminal is used, it may be disconnected when the terminal screw comes loose, resulting in failure.
- Check the rated voltage and signal layout before wiring to the module, and connect the cables correctly. Connecting a power supply with a different voltage rating or incorrect wiring may cause fire or failure.
- Connectors for external devices must be crimped or pressed with the tool specified by the manufacturer, or must be correctly soldered. Incomplete connections may cause short circuit, fire, or malfunction.
- Securely connect the connector to the module. Poor contact may cause malfunction.
- Do not install the control lines or communication cables together with the main circuit lines or power cables. Keep a distance of 100mm or more between them. Failure to do so may result in malfunction due to noise.
- Place the cables in a duct or clamp them. If not, dangling cables may swing or inadvertently be pulled, resulting in malfunction or damage to modules or cables. In addition, the weight of the cables may put stress on modules in an environment of strong vibrations and shocks. Do not clamp the extension cables with the jacket stripped. Doing so may change the characteristics of the cables, resulting in malfunction.
- Check the interface type and correctly connect the cable. Incorrect wiring (connecting the cable to an
 incorrect interface) may cause failure of the module and external device.
- Tighten the terminal screws or connector screws within the specified torque range. Undertightening can cause drop of the screw, short circuit, fire, or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, fire, or malfunction.
- When disconnecting the cable from the module, do not pull the cable by the cable part. For the cable with connector, hold the connector part of the cable. For the cable connected to the terminal block, loosen the terminal screw. Pulling the cable connected to the module may result in malfunction or damage to the module or cable.

[Wiring Precautions]

- Prevent foreign matter such as dust or wire chips from entering the module. Such foreign matter can cause a fire, failure, or malfunction.
- A protective film is attached to the top of the module to prevent foreign matter, such as wire chips, from entering the module during wiring. Do not remove the film during wiring. Remove it for heat dissipation before system operation.
- Programmable controllers must be installed in control panels. Connect the main power supply to the power supply module in the control panel through a relay terminal block. Wiring and replacement of a power supply module must be performed by qualified maintenance personnel with knowledge of protection against electric shock. For wiring, refer to the MELSEC iQ-R Module Configuration Manual.
- For Ethernet cables to be used in the system, select the ones that meet the specifications described in Page 26 Wiring Products. If not, normal data transmission is not guaranteed.

[Startup and Maintenance Precautions]

WARNING

- Do not touch any terminal while power is on. Doing so will cause electric shock or malfunction.
- Correctly connect the battery connector. Do not charge, disassemble, heat, short-circuit, solder, or throw the battery into the fire. Also, do not expose it to liquid or strong shock. Doing so will cause the battery to produce heat, explode, ignite, or leak, resulting in injury and fire.
- Shut off the external power supply (all phases) used in the system before cleaning the module or retightening the terminal screws, connector screws, or module fixing screws. Failure to do so may result in electric shock.

[Startup and Maintenance Precautions]

- When connecting an external device with a CPU module or intelligent function module to modify data of a running programmable controller, configure an interlock circuit in the program to ensure that the entire system will always operate safely. For other forms of control (such as program modification, parameter change, forced output, or operating status change) of a running programmable controller, read the relevant manuals carefully and ensure that the operation is safe before proceeding. Improper operation may damage machines or cause accidents.
- Especially, when a remote programmable controller is controlled by an external device, immediate action cannot be taken if a problem occurs in the programmable controller due to a communication failure. To prevent this, configure an interlock circuit in the program, and determine corrective actions to be taken between the external device and CPU module in case of a communication failure.
- Do not disassemble or modify the modules. Doing so may cause failure, malfunction, injury, or a fire.
- Use any radio communication device such as a cellular phone or PHS (Personal Handy-phone System) more than 25cm away in all directions from the programmable controller. Failure to do so may cause malfunction.
- Shut off the external power supply (all phases) used in the system before mounting or removing the module. Failure to do so may cause the module to fail or malfunction.
- Tighten the screws within the specified torque range. Undertightening can cause drop of the component or wire, short circuit, or malfunction. Overtightening can damage the screw and/or module, resulting in drop, short circuit, or malfunction.

[Startup and Maintenance Precautions]

CAUTION

 After the first use of the product, do not perform each of the following operations more than 50 times (IEC 61131-2/JIS B 3502 compliant):

Exceeding the limit may cause malfunction.

- Mounting/removing the module to/from the base unit
- Inserting/removing the extended SRAM cassette or battery-less option cassette to/from the CPU module
- Mounting/removing the terminal block to/from the module
- After the first use of the product, do not insert/remove the SD memory card to/from the CPU module more than 500 times. Exceeding the limit may cause malfunction.
- Do not touch the metal terminals on the back side of the SD memory card. Doing so may cause malfunction or failure of the module.
- Do not touch the integrated circuits on the circuit board of an extended SRAM cassette or a batteryless option cassette. Doing so may cause malfunction or failure of the module.
- Do not drop or apply shock to the battery to be installed in the module. Doing so may damage the battery, causing the battery fluid to leak inside the battery. If the battery is dropped or any shock is applied to it, dispose of it without using.
- Startup and maintenance of a control panel must be performed by qualified maintenance personnel with knowledge of protection against electric shock. Lock the control panel so that only qualified maintenance personnel can operate it.
- Before handling the module, touch a conducting object such as a grounded metal to discharge the static electricity from the human body. Failure to do so may cause the module to fail or malfunction.

[Operating Precautions]

!CAUTION

- When changing data and operating status, and modifying program of the running programmable controller from an external device such as a personal computer connected to an intelligent function module, read relevant manuals carefully and ensure the safety before operation. Incorrect change or modification may cause system malfunction, damage to the machines, or accidents.
- Do not power off the programmable controller or reset the CPU module while the setting values in the buffer memory are being written to the flash ROM in the module. Doing so will make the data in the flash ROM and SD memory card undefined. The values need to be set in the buffer memory and written to the flash ROM and SD memory card again. Doing so can cause malfunction or failure of the module.

[Disposal Precautions]

CAUTION

- When disposing of this product, treat it as industrial waste.
- When disposing of batteries, separate them from other wastes according to the local regulations. For details on battery regulations in EU member states, refer to the MELSEC iQ-R Module Configuration Manual.

[Transportation Precautions]

- When transporting lithium batteries, follow the transportation regulations. For details on the regulated models, refer to the MELSEC iQ-R Module Configuration Manual.
- The halogens (such as fluorine, chlorine, bromine, and iodine), which are contained in a fumigant used for disinfection and pest control of wood packaging materials, may cause failure of the product. Prevent the entry of fumigant residues into the product or consider other methods (such as heat treatment) instead of fumigation. The disinfection and pest control measures must be applied to unprocessed raw wood.

CONDITIONS OF USE FOR THE PRODUCT

- (1) Mitsubishi programmable controller ("the PRODUCT") shall be used in conditions;
 - i) where any problem, fault or failure occurring in the PRODUCT, if any, shall not lead to any major or serious accident; and
 - ii) where the backup and fail-safe function are systematically or automatically provided outside of the PRODUCT for the case of any problem, fault or failure occurring in the PRODUCT.
- (2) The PRODUCT has been designed and manufactured for the purpose of being used in general industries.

 MITSUBISHI SHALL HAVE NO RESPONSIBILITY OR LIABILITY (INCLUDING, BUT NOT LIMITED TO ANY AND ALL RESPONSIBILITY OR LIABILITY BASED ON CONTRACT, WARRANTY, TORT, PRODUCT LIABILITY) FOR ANY INJURY OR DEATH TO PERSONS OR LOSS OR DAMAGE TO PROPERTY CAUSED BY the PRODUCT THAT ARE OPERATED OR USED IN APPLICATION NOT INTENDED OR EXCLUDED BY INSTRUCTIONS, PRECAUTIONS, OR WARNING CONTAINED IN MITSUBISHI'S USER, INSTRUCTION AND/OR SAFETY MANUALS, TECHNICAL BULLETINS AND GUIDELINES FOR the PRODUCT.

("Prohibited Application")

Prohibited Applications include, but not limited to, the use of the PRODUCT in;

- Nuclear Power Plants and any other power plants operated by Power companies, and/or any other cases in which the public could be affected if any problem or fault occurs in the PRODUCT.
- Railway companies or Public service purposes, and/or any other cases in which establishment of a special quality assurance system is required by the Purchaser or End User.
- Aircraft or Aerospace, Medical applications, Train equipment, transport equipment such as Elevator and Escalator, Incineration and Fuel devices, Vehicles, Manned transportation, Equipment for Recreation and Amusement, and Safety devices, handling of Nuclear or Hazardous Materials or Chemicals, Mining and Drilling, and/or other applications where there is a significant risk of injury to the public or property.

Notwithstanding the above restrictions, Mitsubishi may in its sole discretion, authorize use of the PRODUCT in one or more of the Prohibited Applications, provided that the usage of the PRODUCT is limited only for the specific applications agreed to by Mitsubishi and provided further that no special quality assurance or fail-safe, redundant or other safety features which exceed the general specifications of the PRODUCTs are required. For details, please contact the Mitsubishi representative in your region.

INTRODUCTION

Thank you for purchasing the Mitsubishi Electric MELSEC iQ-R series programmable controllers.

This manual describes the procedures, system configuration, and wiring of the relevant product listed below.

Before using this product, please read this manual and the relevant manuals carefully and develop familiarity with the functions and performance of the MELSEC iQ-R series programmable controller to handle the product correctly.

When applying the program examples provided in this manual to an actual system, ensure the applicability and confirm that it will not cause system control problems.

Please make sure that the end users read this manual.

Relevant product

RJ71EIP91

COMPLIANCE WITH EMC AND LOW VOLTAGE DIRECTIVES

Method of ensuring compliance

To ensure that Mitsubishi programmable controllers maintain EMC and Low Voltage Directives when incorporated into other machinery or equipment, certain measures may be necessary. Please refer to one of the following manuals.

- MELSEC iQ-R Module Configuration Manual
- · Safety Guidelines (This manual is included with the base unit.)

Additional measures

To ensure that this product maintains EMC and Low Voltage Directives, please refer to one of the following manuals.

- MELSEC iQ-R Module Configuration Manual
- · Safety Guidelines (This manual is included with the base unit.)

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RELEVANT MANUALS

Manual name [manual number]	Description	Available form
MELSEC iQ-R EtherNet/IP Network Interface Module	Specifications, procedures before operation, system configuration, wiring, and	Print book
User's Manual (Startup) [SH-081913ENG] (this manual)	· ·	
MELSEC iQ-R EtherNet/IP Network Interface Module	Functions, parameter settings, operation methods of EtherNet/IP Configuration	
User's Manual (Application) [SH-081915ENG]	Tool, programming, troubleshooting, I/O signals, and buffer memory of the EtherNet/IP network interface module	e-Manual PDF
GX Works3 Operating Manual [SH-081915ENG]	System configuration, parameter settings, and online operations of GX Works3	e-Manual PDF
MELSEC iQ-R EtherNet/IP Network Interface Module Function Block Reference [BCN-P5999-0942]	Specifications of the FBs, functions, and I/O labels of the EtherNet/IP network interface module	e-Manual PDF

This manual does not include detailed information on the following:

- · General specifications
- · Applicable combinations of CPU modules and the other modules, and the number of mountable modules
- Installation

For details, refer to the following.

MELSEC iQ-R Module Configuration Manual



e-Manual refers to the Mitsubishi Electric FA electronic book manuals that can be browsed using a dedicated tool.

e-Manual has the following features:

- Required information can be cross-searched in multiple manuals.
- Other manuals can be accessed from the links in the manual.
- The hardware specifications of each part can be found from the product figures.
- Pages that users often browse can be bookmarked.
- Sample programs can be copied to an engineering tool.

TERMS

Unless otherwise specified, this manual uses the following terms.

Term	Description	
Adapter	A station type of EtherNet/IP that corresponds to slave stations	
Buffer memory	A memory in an intelligent function module, where data (such as setting values and monitoring values) are stored. When integrated into the CPU module, this memory refers to a memory for storing data such as setting values and monitored values of the Ethernet function, and data used for data communication of the multiple CPU system function.	
Consumer Tag	Consumed tag	
Device	A device (X, Y, M, D, or others) in a CPU module	
Engineering tool	A tool used for setting up programmable controllers, programming, debugging, and maintenance	
EtherNet/IP Configuration Tool	EtherNet/IP Configuration Tool for RJ71EIP91. A tool for setting the network configuration for EtherNet/IP.	
EtherNet/IP device	Devices, personal computers, and other equipment connected via EtherNet/IP for data communication	
Global label	A label that is valid for all the program data when multiple program data are created in the project. There are two types of global label: a module specific label (module label), which is generated automatically by GX Works3, and an optional label, which can be created for any specified device.	
Intelligent function module	A module that has functions other than input and output, such as an A/D converter module and D/A converter module	
Label	A label that represents a device in a given character string	
Module label	A label that represents one of memory areas (I/O signals and buffer memory areas) specific to each module in a given character string. For the module used, GX Works3 automatically generates this label, which can be used as a global label.	
Originator	An EtherNet/IP device that transmits a connection establishment request of EtherNet/IP	
PPS	Packets Per Second. The number of packets that can be processed per second.	
Producer Tag	Produced tag	
RPI	Requested Packet Interval. A communication cycle that is decided by the originator during communications between EtherNet/IP devices.	
Scanner	A station type of EtherNet/IP that corresponds to the master station	
Target	An EtherNet/IP device that receives a connection establishment request of EtherNet/IP	

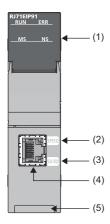
GENERIC TERMS AND ABBREVIATIONS

Unless otherwise specified, this manual uses the following generic terms and abbreviations.

Generic term and abbreviation	Description
CPU module	A generic term for the MELSEC iQ-R series CPU modules

PART NAMES

This chapter describes the names of each part of the RJ71EIP91.



No.	Name	Description
(1)	RUN LED	Indicates the operating status. On: Normal operation Flashing: Initial processing Off: Error (A MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application))
	ERR LED	Indicates the error status of the module. On, flashing: Error (MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application)) Off: Normal operation
	MS LED*1	Indicates the error status of the EtherNet/IP device. On (green): Data communication possible On (red): Moderate error or major error Flashing (red): Minor error
	NS LED*1	Indicates the EtherNet/IP network status. On (green): Data communications being performed Flashing (green): Failed to establish connection
(2)	SPEED LED	Indicates the EtherNet/IP link status. On (orange): Link-up (1Gbps) On (green): Link-up (100Mbps) Off: Link-down
(3)	SD/RD LED	Indicates the EtherNet/IP data sending/receiving status. On: Data being sent or received Off: Data not transmitted or received
(4)	Ethernet port	A connector for EtherNet/IP. Connect an Ethernet cable. For wiring method and wiring precautions, refer to the following. Page 25 WIRING
(5)	Production information marking	Shows the production information (16 digits) of the module.

^{*1} At power-on, MS LED and NS LED turn on in green \rightarrow red, but this behavior is not a malfunction.

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2 SPECIFICATIONS

2.1 Performance Specifications

The following table lists the performance specifications of the RJ71EIP91.

Item	<u>'</u>		Description
			•
EtherNet/IP communications	Class 1 communications	Communication format	Standard EtherNet/IP, tag communications
		Number of connections	Standard EtherNet/IP: 256*1 Tag communications: 256*1
		Communication data size	1444 bytes (per connection)
		Connection type	Point-to-point, multicast
		RPI (communication cycle)	0.5 to 60000ms
		PPS (communication	12000PPS
		processing performance)	12000PPS
	Class 3	Communication format	Standard EtherNet/IP
	communications	Number of connections	Server: 256*1 Client: None
		Communication data size	1414 bytes (per connection)
		Connection type	Point-to-point
	UCMM	Communication format	Standard EtherNet/IP
	communications	Number of connections (number of simultaneous executions)	• Server: 96 • Client: 32
		Communication data size	1414 bytes
		Connection type	Point-to-point
Transmission	Number of ports		1
specifications	Communication mode		Full-duplex
	Data transmission speed		100Mbps
	Transmission method		Base band
	Maximum segment length		100m (length between hub and node)*2
	Number of cascade connections		Consult the manufacturer of the switching hub used.
	Interface		RJ45 connector
	IP version		IPv4 is supported.
Number of occupied I/O points			32
Internal current consumption (5VDC)			1.09A
External dimensions	Height		106mm (base unit mounting side: 98mm)
	Width		27.8mm
	Depth		110mm
Weight			0.24kg

^{*1} The total number of connections for Class 1 communications and Class 3 communications is 256.

^{*2} For maximum segment length (length between hubs), consult the manufacturer of the hub used.

MEMO

3 FUNCTION LIST

The following table lists the functions of the RJ71EIP91. For details on the functions, refer to the following.

MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application)

EtherNet/IP communication functions

Function	Description
Class1 instance communications	Periodically performs data communications between the RJ71EIP91 and the EtherNet/IP device to which the connection has been established using an instance ID. This function is used for performing cyclic (Implicit) communications with an adapter. Data communications are performed between the originator that transmits the connection request and the target that receives the connection request.
Class1 tag communications	Performs data communications between the RJ71EIP91 modules to which the connection has been established using a tag name. This function is used for performing cyclic (Implicit) communications between scanners supported tag communications on the programmable controller. Data communications are periodically performed between tags that have the same Tag name and the same Data Size using Producer Tag and Consumer Tag.
Class3 message communications	Performs message (Explicit) communications between the RJ71EIP91 and the EtherNet/IP device to which the connection has been established by specifying a message (Explicit) communication destination using an instance ID. Class3 message communications support the server function.
UCMM message communications	Performs message (Explicit) communications between the RJ71EIP91 and the EtherNet/IP device by specifying a message (Explicit) communication destination using an instance ID without establishing the connection. UCMM message communications support the client function and the server function.

Others

Function	Description
Communication status setting function at the occurrence of a CPU stop error	Sets whether to stop or continue EtherNet/IP communications when a stop error occurs on the CPU module to which the RJ71EIP91 is mounted. This setting can be made for each module.

MEMO

4

PROCEDURES BEFORE OPERATION

This chapter describes the procedures before operation.

1. Mounting the module to the base unit

The RJ71EIP91 has no module fixing hooks. For how to mount/remove a module having no module fixing hooks to/from the base unit, refer to the following.

MELSEC iQ-R Module Configuration Manual

2. Network configuration

Configure the system and set the parameters that are required for start-up.

- Wiring (Page 25 WIRING)
- Parameter settings (MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application))

3. Network diagnostics

Check the connection status of the connected EtherNet/IP device using EtherNet/IP Configuration Tool.

For details, refer to the following.

MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application)

4. Programming

Create a program. For details, refer to the following.

Page 28 COMMUNICATION EXAMPLE

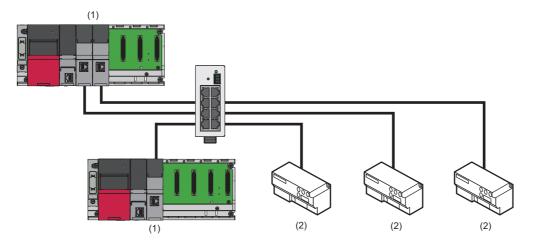
MEMO

5 SYSTEM CONFIGURATION

5.1 EtherNet/IP Configuration

EtherNet/IP consists of the RJ71EIP91 (1) and EtherNet/IP devices (2).

Connect the modules in a star topology using a switching hub and Ethernet cables. Line and ring topologies are not possible.





In EtherNet/IP, other external devices that perform TCP/IP communications can be used with the devices on the same network.

Scanner and adapter

In EtherNet/IP, station types are separated into scanner and adapter.

Station type	Description
Scanner	A station type of EtherNet/IP that corresponds to the master station. The scanner has the control information and controls the overall network. Devices that have a connection of originator or target can be operated as the scanner.
Adapter	A station type of EtherNet/IP that corresponds to slave stations. The adapter indicates stations other than the scanner. Devices that have a connection of target can be operated as the adapter.

5.2 Available Software Packages

To configure the settings of the RJ71EIP91, the engineering tool and EtherNet/IP Configuration Tool are required.

Software	Supported version
GX Works3	Version 1.045X or later
EtherNet/IP Configuration Tool	Version 1.00A or later

EtherNet/IP Configuration Tool

Please consult your local Mitsubishi representative to obtain EtherNet/IP Configuration Tool.

■Operating environment, installation/uninstallation

For the operating environment and installation/uninstallation of EtherNet/IP Configuration Tool, refer to the following.

EtherNet/IP Configuration Tool Installation Instructions

■Operation methods and functions

For the operation methods and functions of EtherNet/IP Configuration Tool, refer to the following.

MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application)

■Profile of the RJ71EIP91

Profile is data in which the information (such as models) of the connected devices is stored.

The profile of the RJ71EIP91 is automatically registered in GX Works3 at the installation of EtherNet/IP Configuration Tool.



If GX Works3 is installed when EtherNet/IP Configuration Tool has already been installed, the RJ71EIP91 cannot be added in GX Works3.

Install GX Works3, then EtherNet/IP Configuration Tool.

■EDS file

For EDS file, download from Mitsubishi Electric FA Global Site.

www.MitsubishiElectric.com/fa

6 WIRING

This chapter describes the wiring for EtherNet/IP.

6.1 Wiring Method

This section describes how to connect and disconnect the Ethernet cable.

Connecting the cable

- 1. Push the Ethernet cable connector into the RJ71EIP91 until it clicks. Pay attention to the orientation of the connector.
- 2. Lightly pull the connector to check that the connector is securely connected.
- **3.** Check whether the SPEED LED of the port connected with an Ethernet cable is on.*1
- *1 The time between the cable connection and the turning on of the SPEED LED may vary. The SPEED LED usually turns on in a few seconds. Note, however, that the time may be extended further if the link-up processing is repeated depending on the status of the device on the line. Check whether the cables are connected properly if the SPEED LED does not turn on. (MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application))

Disconnecting the cable

1. Unplug the Ethernet cable while pressing the latch connector down.

Precautions

- Place the Ethernet cable in a duct or clamp it. Failure to do so may lead to swinging or inadvertent pulling of dangling cable, resulting in damage to the module or the cable or malfunction due to poor contact.
- Do not touch the core of the cable-side or module-side connector, and protect them from dirt or dust. If oil on your hands, dirt, or dust adheres to the core, transmission loss may increase, causing communication problems.
- · Check that the Ethernet cable is not disconnected or not shorted and check that the cable is connected properly.
- Do not use Ethernet cables with broken latch connectors. Doing so may cause the Ethernet cables to be disconnected or the module to malfunction.
- Hold the connector part of the Ethernet cable when connecting and disconnecting it. Pulling the cable connected to the module may result in damage to the module or the cable or malfunction due to poor contact.
- The maximum segment length of the Ethernet cable is 100m. However, the acceptable length may be shorter depending on the environment where the cable is used. For details, contact the cable manufacturer.
- The bending radius of the Ethernet cable is limited. For details, check the specifications of the Ethernet cable to be used.
- The recommended maximum number of cascade connections is three. Four or more connections increase the possibility of packet loss caused by the switching hub.

6.2 Wiring Products

This section describes the devices used to comprise EtherNet/IP.

Ethernet cable

Use Ethernet cables that meet the following standards.

Communication speed	Ethernet cable	Connector	Standard
100Mbps	Category 5 or higher, (shielded STP) straight cable	RJ45 connector	100BASE-TX



Depending on the connection environment, communication errors may occur due to high-frequency noise from devices other than programmable controllers. The following describes precautionary measures to be taken on the RJ71EIP91 to avoid the influence of high-frequency noise.

- When wiring cables, do not bundle them together with or keep them in close proximity to the main circuit lines or power cables.
- · Place cables in a duct.
- Use STP cables in place of UTP cables.

Hub

When using hubs for EtherNet/IP, use hubs that support the transmission speed of communications.

7 COMMUNICATION EXAMPLE

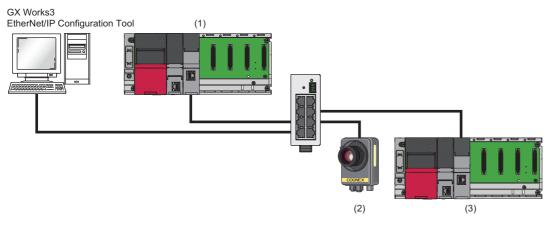
7.1 Communication Example between RJ71EIP91 and EtherNet/IP Device

This section describes examples of Class 1 instance communications and Class 1 tag communications between the RJ71EIP91 and an EtherNet/IP device.

System configuration example

The following system configuration is used to for the examples of Class 1 instance communications and Class 1 tag communications.

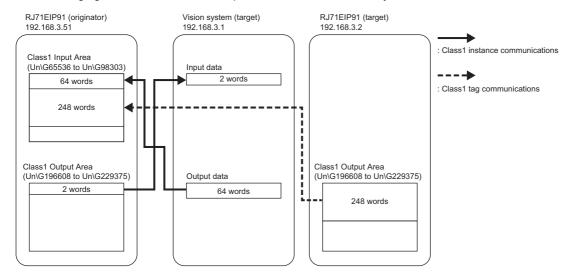
System configuration



- (1) Programmable controller system (originator)
- Power supply module: R61P
- CPU module: R04CPU
- EtherNet/IP network interface module: RJ71EIP91 (start I/O number: 0000H to 001FH, IP address: 192.168.3.51)
- (2) EtherNet/IP device (target)
- Vision system (IP address: 192.168.3.1)*1
- (3) Programmable controller system (target)
- Power supply module: R61P
- CPU module: R04CPU
- EtherNet/IP network interface module: RJ71EIP91 (start I/O number: 0000H to 001FH, IP address: 192.168.3.2)
- *1 This device is manufactured by Cognex Corporation.

Communication description

The following figure shows the relationship between the buffer memory areas of the RJ71EIP91 and each target.



Setting parameters

Set the parameters using the engineering tool and EtherNet/IP Configuration Tool.

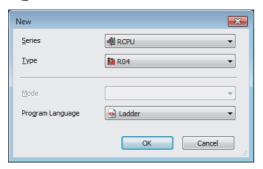
Setting the engineering tool

■Setting the RJ71EIP91 (originator)

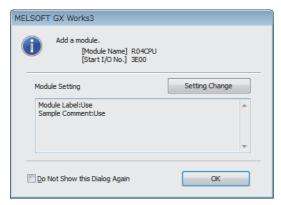
Connect the engineering tool to the scanner-side CPU module and set the parameters.

1. Set the CPU module as follows.

(Project] ⇒ [New]

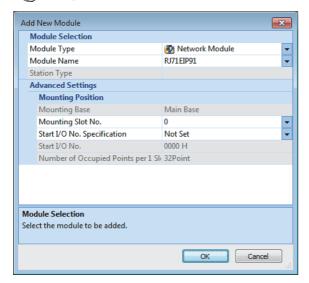


- 2. Click the [Setting Change] button to use the module label.
- Click the [OK] button to add the module labels of the CPU module.

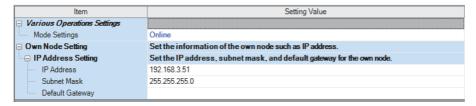


- 4. Set the RJ71EIP91 as follows.
- [Navigation window]

 □ [Parameter]
 □ [Module Information]
 □ Right-click
 □ [Add New Module]



- 5. Set the items in "Basic Setting" as follows.
- [Navigation window] ⇒ [Parameter] ⇒ [Module Information] ⇒ [RJ71EIP91] ⇒ [Basic Setting]



6. Write the set parameters to the CPU module. Then reset the CPU module or power off and on the system.

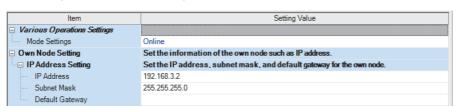
[Online] ⇒ [Write to PLC]

■Setting the RJ71EIP91 (target)

Connect the engineering tool to the adapter-side CPU module and set the parameters.

The setting procedure is the same as steps 1 to 5 for the RJ71EIP91 (originator). (Page 30 Setting the RJ71EIP91 (originator))

The setting items in "Basic Setting" are shown below.

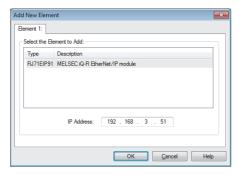


Setting EtherNet/IP Configuration Tool

Start EtherNet/IP Configuration Tool, and then set the parameters.

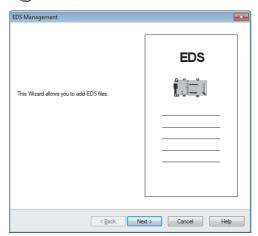
■IP address setting of the RJ71EIP91 (originator)

Set the IP address in the "Add New Element" window that is popped up when EtherNet/IP Configuration Tool is started. Set the same IP address as that set in "Basic Setting" in the engineering tool.

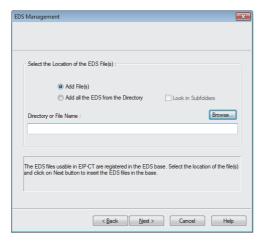


■Adding the EDS file

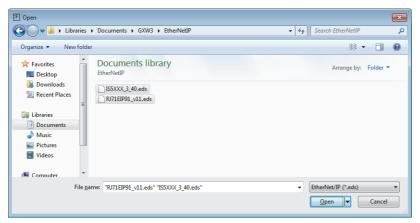
- 1. Open the "EDS Management" window to add an EDS file for the EtherNet/IP device to "Device Library".
- [Library]
 □ [Add]



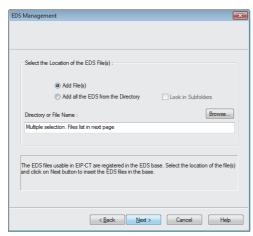
- 2. Click the [Next] button in the "EDS Management" window.
- 3. Click the [Browse] button.



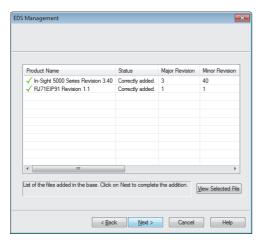
4. Select the EDS file and click the [Open] button.



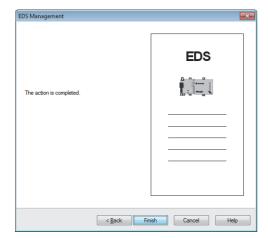
5. Click the [Next] button.



6. The addition result of the EDS file to "Device Library" is displayed. Click the [Next] button.



7. Click the [Finish] button to exit the EDS Management wizard.

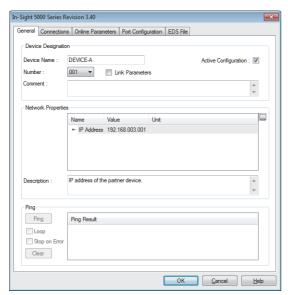


■EtherNet/IP device setting of the RJ71EIP91 (originator)

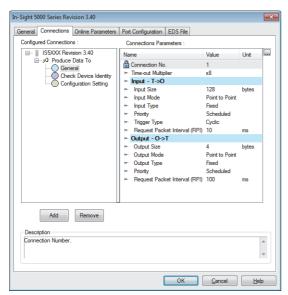
- 1. Select the EtherNet/IP device in "Device Library" to add it to the network configuration setting.
- Select the EtherNet/IP device in "Device Library"

 □ [Library]

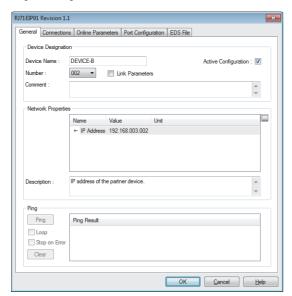
 □ [Insert in Configuration]
- · [General] tab



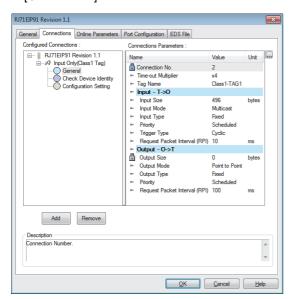
- 2. Configure the Class 1 instance communication settings for the connection 1 EtherNet/IP device.
- Select the EtherNet/IP device in the network configuration setting ⇒ [Devices] ⇒ [Properties]
- · [Connections] tab



- 3. Configure the Class 1 tag communication settings for the connection 2 EtherNet/IP device.
- Select the EtherNet/IP device in the network configuration setting ⇒ [Devices] ⇒ [Properties]
- · [General] tab



• [Connections] tab



- 4. Switch the engineering tool to the online state.
- [File] ⇒ [Go Online]
- **5.** Write the set parameters to the RJ71EIP91.
- [File] ⇒ [Download]



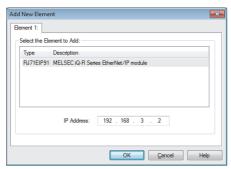
■Setting the RJ71EIP91 (target)

- 1. Create a new project in the "Configuration Manager" window.
- Right-click "EtherNet/IP Network" in the EtherNet/IP setting.

 □ [Configuration Manager] □ [New] button

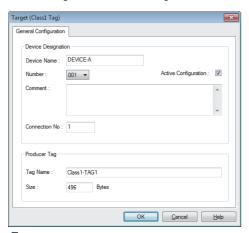


2. Set the IP address of the RJ71EIP91 (target).



- 3. Select the target in "Device Library" to add it to the network configuration setting.
- Select the "Target(Class1 Tag)" in "Device Library".

 □ [Library] □ [Insert in Configuration]
- 4. Configure the Class 1 tag communication settings for the RJ71EIP91 (target).



- **5.** Switch the engineering tool to the online state.
- (File] ⇒ [Go Online]

6. Write the set parameters to the RJ71EIP91.







- Set the IP addresses for the personal computer connected to the RJ71EIP91 so that they have the same class and subnet address.
- For the Class1 tag communication settings, match a Tag name and data size of the RJ71EIP91 (originator) by those of the RJ71EIP91 (target).
- In the program example, default values are used for parameters that are not shown above. For the parameters, refer to the following.

MELSEC iQ-R EtherNet/IP Network Interface Module User's Manual (Application)

Network status check

Check whether the RJ71EIP91 and the EtherNet/IP device can communicate with each other normally. Communications are performed normally if the status of the LEDs is as shown below.

LED	Status
RUN LED	On
ERR LED	Off
MS LED	On (green)
NS LED	On (green)

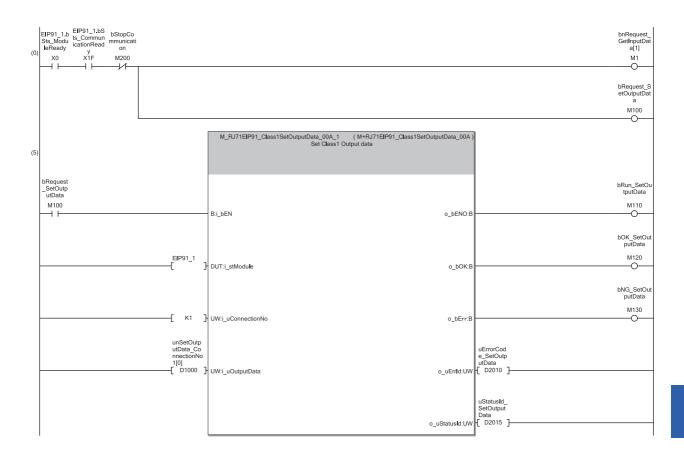
Program example

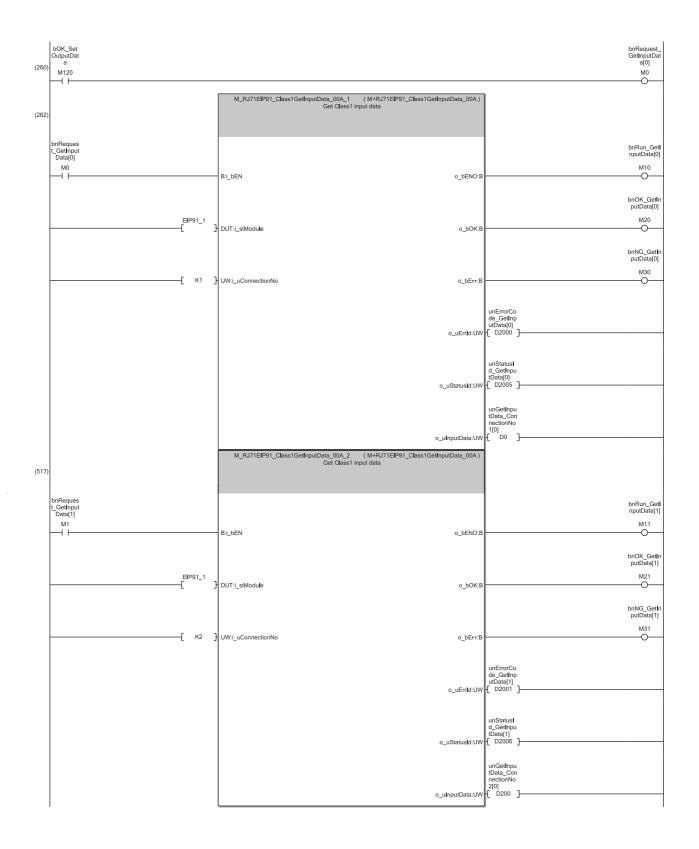
The following program executes Class1 instance communications and the Class1 tag communications by executing STOP \rightarrow RUN on the CPU module.

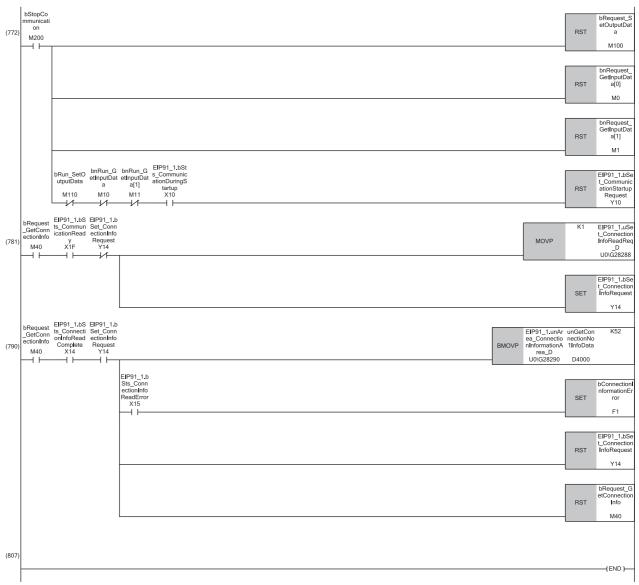
In addition, the following program reads the connection information by turning on the connection information read request command in the program.

Program of the RJ71EIP91 (originator)

lassification	Label name			Descriptio	Description		
Module label	EIP91_1.bSts_ModuleReady			Module Read	Module Ready		
	EIP91_1.bSts_CommunicationDuringStartup			EtherNet/IP communication in process			X10
	EIP91_1.bSts_ConnectionInfoReadComplete			Connection information read completion			X14
	EIP91_1.bSts_ConnectionIn	EIP91_1.bSts_ConnectionInfoReadError			Connection information read error		
	EIP91_1.bSts_CommunicationReady			Communicat	Communication Ready		
	EIP91_1.bSet_Communicat	EIP91_1.bSet_CommunicationStartupRequest			comi	munication start request	Y10
	EIP91_1.bSet_ConnectionIr	foRequest		Connection i	nfor	nation read request	Y14
	EIP91_1.uSet_ConnectionIr	EIP91_1.uSet_ConnectionInfoReadReq_D			nfor	nation request area	U0\G28288
	EIP91_1.unArea_Connectio	EIP91_1.unArea_ConnectionInformationArea_D			nfor	nation area	U0\G28290
	EIP91_1			Module label			_
Label to be	Define global labels as show	n below.					
defined	Label Name	Data Type		Class		Assign (Device/Label)	
	bnRequest GetInputData	Bit (01)		VAR_GLOBAL		M0	
	bnRun GetInputData	Bit (01)		VAR GLOBAL		M10	
	bnOK GetInputData	Bit (01)		VAR_GLOBAL		M20	
	bnNG GetInputData	Bit(01)		VAR GLOBAL		M30	
	unErrorCode_GetInputData	Word [Unsigned]/Bit String [16-bit](01)		VAR_GLOBAL		D2000	
	unStatusId_GetInputData	Word [Unsigned]/Bit String [16-bit](01)		VAR_GLOBAL		D2005	
	unGetInputData ConnectionNo1	Word [Unsigned]/Bit String [16-bit](063)		VAR_GLOBAL		D0	
	unGetInputData ConnectionNo2	Word [Unsigned]/Bit String [16-bit](0127)		VAR GLOBAL		D200	
	unSetOutputData ConnectionNo1	Word [Unsigned]/Bit String [16-bit](01)		VAR_GLOBAL	_	D1000	
	bRequest_SetOutputData	Bit		VAR GLOBAL		M100	
	bRun SetOutputData	Bit		VAR GLOBAL		M110	
	bOK_SetOutputData	Bit		VAR_GLOBAL		M120	
	bNG SetOutputData	Bit		VAR GLOBAL		M130	
	uErrorCode_SetOutputData	Word [Unsigned]/Bit String [16-bit]		VAR_GLOBAL		D2010	
	uStatusId SetOutputData	Word [Unsigned]/Bit String [16-bit]		VAR GLOBAL		D2015	
	bStopCommunication	Bit		VAR GLOBAL		M200	
	bRequest GetConnectionInfo	Bit		VAR GLOBAL		M40	
	unGetConnectionNo1InfoData	Word [Unsigned]/Bit String [16-bit](051)		VAR GLOBAL		D4000	
	bConnectionInformationError	Bit		VAR GLOBAL	-		



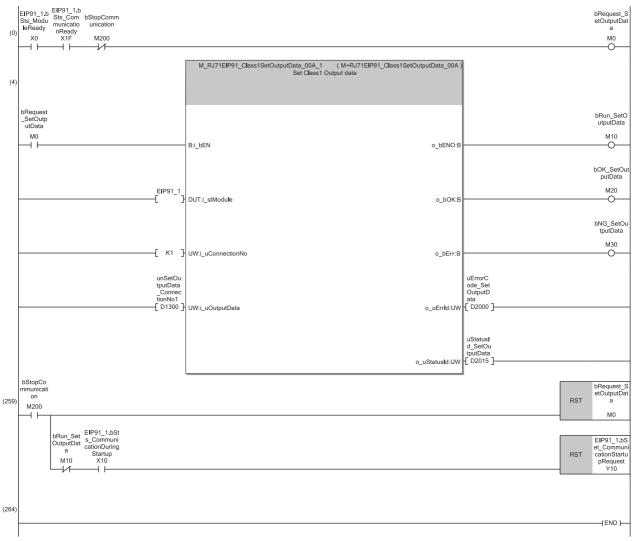




- (0) Start communications, and then acquire input data and set output data.
- (5) Set output data on the connection number 1.
- (262) Acquire input data on the connection number 1 when the output data setting is configured correctly.
- (517) Acquire input data on the connection number 2.
- (772) Turn on M200 to stop the acquisition processing of input data or the setting processing of output data or to stop communication processing. However, communication processing is stopped when 'EtherNet/IP data link continuation specification state' (Un\G16635) is "2: Operation is in progress with the setting for stopping EtherNet/IP communication".
- (781) Set the connection number in the connection number specification.
- (790) Store the data from which the connection information is read.

Program of the RJ71EIP91 (target)

Classification	Label name				Description			Device
Module label	EIP91_1.bSts_ModuleReady				Module Ready			X0
	EIP91_1.bSts_Communicat	P91_1.bSts_CommunicationDuringStartup				P communication in	X10	
	EIP91_1.bSts_CommunicationReady				Communication Ready			X1F
	EIP91_1.bSet_Communicat	IP91_1.bSet_CommunicationStartupRequest				P communication sta	Y10	
	EIP91_1				Module label			_
Label to be	Define global labels as shown below.							
defined	Label Name	Data Type		Cla	ass	Assign (Device/Labe)	
	bStopCommunication	Bit	T	VAR_GLO	BAL •	M200		
	bRun_SetOutputData	Bit		VAR_GLO	BAL ¬	M10		
	bRequest_SetOutputData	Bit		VAR_GLO	BAL •	M0		
	bOK_SetOutputData	Bit		VAR_GLO	BAL ¬	M20		
	bNG_SetOutputData	Bit		VAR_GLO	BAL -	M30		
	unSetOutputData_ConnectionNo1	Word [Unsigned]/Bit String [16-bit](0127)		VAR_GLO	BAL -	D1300		
	uErrorCode_SetOutputData	Word [Unsigned]/Bit String [16-bit]		VAR_GLO		D2000		
	uStatusId_SetOutputData	Word [Unsigned]/Bit String [16-bit]		VAR_GLO	BAL -	D2015		

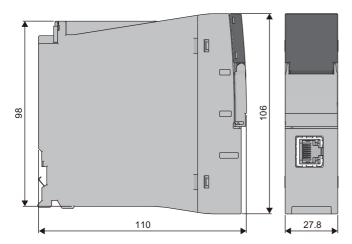


- $\begin{tabular}{ll} (0) Start communications, and set output data on the connection number 1. \end{tabular}$
- (4) Acquire input data on the connection number 1.
- (259) Turn on M200 to stop the acquisition processing of input data or the setting processing of output data or to stop communication processing. However, communication processing is stopped when 'EtherNet/IP data link continuation specification state' (Un\G16635) is "2: Operation is in progress with the setting for stopping EtherNet/IP communication".

APPENDIX

Appendix 1 External Dimensions

This section describes the external dimensions of the RJ71EIP91.



(Unit: mm)

MEMO

A

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Adapter	Weight
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Transmission method	
U	
UCMM message communications	

REVISIONS

*The manual number is given on the bottom left of the back cover.

Revision date	*Manual number	Description
May 2018	SH(NA)-081913ENG-A	First edition
August 2019	SH(NA)-081913ENG-B	■Added or modified parts TERMS, Section 2.1, 7.1
October 2019	SH(NA)-081913ENG-C	■Added or modified parts SAFETY PRECAUTIONS, COMPLIANCE WITH EMC AND LOW VOLTAGE DIRECTIVES, RELEVANT MANUALS, TERMS, GENERIC TERMS AND ABBREVIATIONS, Chapter 3, Section 6.1 ■Deleted part Section 5.2

Japanese manual number: SH-081912-C

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WARRANTY

Please confirm the following product warranty details before using this product.

1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company.

However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing on-site that involves replacement of the failed module.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place. Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 - 1. Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 - 2. Failure caused by unapproved modifications, etc., to the product by the user.
 - When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 - 4. Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 - 5. Failure caused by external irresistible forces such as fires or abnormal voltages, and Failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 - 6. Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 - 7. Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

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- (1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued. Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- (2) Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation to:

- (1) Damages caused by any cause found not to be the responsibility of Mitsubishi.
- (2) Loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products.
- (3) Special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products.
- (4) Replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

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<u>SH(NA)-081913ENG-C(1910)MEE</u> MODEL: RJ71EIP91-U-IN-E

MODEL CODE: 13JX83

MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE : TOKYO BUILDING, 2-7-3 MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN NAGOYA WORKS : 1-14 , YADA-MINAMI 5-CHOME , HIGASHI-KU, NAGOYA , JAPAN

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